Statistical Mechanics of Small Systems

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Using the determinental form of the N-V-T and N-P-T partition functions, we derive explicit expressions for the N-dependent virial coefficients occurring in the expansions of the equations of state in the N-V-T and N-P-T ensembles. The results are presented in a matrix algebra formalism. The equation of state of N hard spheres in an N-P-T ensemble of systems is analyzed by the method of Padé Approximants.

I. INTRODUCTION

In recent years the development of computer-simulated physical systems has created a need for theories to relate the machine-determined properties of these finite systems to the properties of similar infinite systems [1, 2]. The equation of state for a classical fluid whose molecules interact with pairwise additive forces has been analyzed by Oppenheim and Mazur [3] and also by Lebowitz and Percus [4]. In the latter paper the pressure P(N, V) exerted on the walls of a periodic box of volume V by N particles was expressed as a power series in the number density $\rho = N/V$ and the coefficient of ρ^l was found to be a complicated function of N and V which could be explicitly determined only in a relatively low density region. The general result was that the coefficient of ρ^l $(l \leq N)$ could be expressed as a polynomial of order (l-1) in 1/N, the coefficient of N^{-j} $(j \leq l-1)$ being a function of the connected cluster integrals b_k' $(k \leq l)$. For a periodic parallelepiped or rectangular box b_l' was an implicit function of V for l > L/a, a being the range of the intermolecular forces and L the length of the smallest edge of the box.

In this paper we are mainly concerned with the b_l for l < L/a so that the connected cluster integrals become the volume independent integrals b_l . A matrix algorithm is developed for generating the N dependent virial coefficients occurring in the density expansion of the canonical pressure. A similar analysis is performed on the N-P-T equation of state, \overline{V}/N being the dependent variable and P/k_BT the independent variable, where k_B is Boltzmann's constant and T is the absolute temperature. The N-dependent virial coefficients have a particularly simple form

in the *N*-*P*-*T* formalism, that of a polynomial of order 1 in 1/N for the *l*th coefficient, $l \leq N + 1$. In other words, the coefficients are of the form $a_l + d_l/N$, $l \leq N + 1$, where a_l , d_l are functions of the connected cluster integrals b_l .

We compare the condition $l \leq N$ to that necessary in the N-V-T ensemble for volume-independent virial coefficients, that in the expansion [5]

$$P/k_BT = \sum_{l=1}^{N} B_l'(N, V) \rho^l$$
 (I.1)

the B_l' are not functions of V for $l \leq L/a$, or assuming the box to be cubical, $l \leq (N/\rho a^3)^{1/3}$. The two conditions $l \leq N$ (N-P-T) and $l \leq (N/\rho a^3)^{1/3}$ (N-V-T) are qualitatively different because the independent variable P/k_BT does not appear in the former inequality while the independent variable ρ does appear in the latter inequality.

Thus if we consider a fluid under high compression in a periodic box with small N we would expect the P/k_BT expansion in the N-P-T ensemble to be easier to formulate than the ρ expansion in the N-V-T ensemble. With this in mind we analyze the N-P-T equation of state for hard spheres using the method of Padé Approximants. The purpose of this analysis is to provide some quantitative information about the properties of finite N-P-T systems with the hope that it may be useful in interpreting computer experiments performed in the N-P-T ensemble.

II. A MATRIX FORMULA FOR THE N-V-T VIRIAL COEFFICIENTS

We start with the product representation of Q(N, V, T), the canonical partition function, in terms of the connected cluster integrals b_l' , with *l* between 1 and N [6].

$$Q(N, V, T) = \frac{1}{\Lambda^{3N}} \sum_{\{m_l\}} \prod_{l=1}^{\prime} \frac{(Vb_l)^{m_l}}{m_l!},$$
$$\Lambda = (h^2/2\pi mk_B T)^{1/2}.$$
(II.1)

The summation in Eq. (II.1) is carried out over all sets of nonnegative integers $\{m_l\} = \{m_1, m_2, ..., m_l\}$ which satisfy the restrictions

$$\sum lm_l = N. \tag{II.2}$$

A decomposition similar to Eq. (II.1) can be obtained for the quantum mechanical case and also for many body forces [7], but from here on we shall concern ourselves only with classical statistics and pairwise additive forces. This simplification

enables us to define unambiguously the condition

$$b_l' = b_l \quad \text{if} \quad l < L/a, \tag{II.3}$$

when the system is enclosed by a periodic box. We shall assume that Eq. (II.3) holds throughout the remainder of this section.

Equation (II.1) can be expressed as a determinant [8]:

$$Q(N, V, T) = \frac{1}{A^{3N}N!} \begin{vmatrix} Vb_1 & -1 & 0 & 0 & \cdots & 0\\ 2Vb_2 & Vb_1 & -2 & 0 & \cdots & 0\\ 3Vb_3 & 2Vb_2 & Vb_1 & -3 & \cdots & 0\\ \vdots & \vdots & \vdots & \vdots & & \vdots\\ NVb_N & (N-1)Vb_{N-1} & (N-2)Vb_{N-2} & (N-3)Vb_{N-3} & \cdots & Vb_1 \end{vmatrix}_N$$
(II.4)

which is a new result.

Expressing Eq. (II.4) in terms of the number density ρ , we have

$$Q(N, V, T) = \frac{(\rho^{-1}N)^{N}}{\Lambda^{3N}N!} \det \mathbf{M}_{N},$$

$$\mathbf{M}_{N} = \begin{cases} b_{1} & -\rho N^{-1} & 0 & 0 & \cdots & 0\\ 2b_{2} & b_{1} & -2\rho N^{-1} & 0 & \cdots & 0\\ 3b_{3} & 2b_{2} & b_{1} & -3\rho N^{-1} & \cdots & 0\\ \vdots & \vdots & \vdots & \vdots & \vdots\\ Nb_{N} & (N-1)b_{N-1} & (N-2)b_{N-2} & (N-3)b_{N-3} & \cdots & b_{1} \end{cases} , \quad (\text{II.5})$$

The equation of state may be written as

$$\frac{P}{k_B T} = -\frac{\rho^2}{N} \left(\frac{\partial \ln Q(N, V, T)}{\partial \rho}\right)_{T,N}$$

$$= \rho - \frac{\rho^2}{N} \left(\frac{\partial \ln \Delta_N}{\partial \rho}\right)_{T,N}$$
(II.6)

where Δ_N represents det \mathbf{M}_N .

From matrix algebra, we have

$$\left(\frac{\partial \ln \Delta_N}{\partial \rho}\right)_{T,N} = \operatorname{Trace}\left[\mathbf{M}_N^{-1} \cdot \left(\frac{\partial \mathbf{M}_N}{\partial \rho}\right)_{T,N}\right], \quad (II.7)$$

504

where \mathbf{M}_N^{-1} is the inverse of the matrix \mathbf{M}_N [9]. Since the b_l are independent of ρ , we may write

$$\left(\frac{\partial \mathbf{M}_{N}}{\partial \rho}\right)_{T,N} = \mathbf{T}_{N} = -\frac{1}{N} \begin{cases} 0 & 1 & 0 & 0 & \cdots & 0\\ 0 & 0 & 2 & 0 & \cdots & 0\\ 0 & 0 & 0 & 3 & \cdots & 0\\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots\\ 0 & 0 & 0 & 0 & \cdots & 0 \end{cases}_{N}$$
(II.8)

The virial coefficients are obtained by expanding Eq. (II.7) in powers of ρ (assuming ρ to be small), the result being

$$\frac{P}{k_B T} = \sum_{l=1}^{N} B_l(N) \rho^l = \rho + \sum_{l=2}^{N} \frac{(-1)}{N(l-2)!} \frac{\partial^{l-2}}{\partial \rho^{l-2}} \left(\operatorname{Tr} \mathbf{M}_N^{-1} \cdot \mathbf{T}_N \right) \Big|_{\rho=0} \rho^l$$
$$= \rho + \sum_{l=2}^{N} \frac{(-1)}{N(l-2)!} \operatorname{Tr} \left[\left(\frac{\partial^{l-2} \mathbf{M}_N^{-1}}{\partial \rho^{l-2}} \right)_{\rho=0} \cdot \mathbf{T}_N \right] \rho^l.$$
(II.9)

Equation (II.9) is still in a rather complex form because the inverse of \mathbf{M}_N must be calculated. This problem can be simplified by converting Equation (II.9) to a form that contains the inverse of an $N \times N$ triangular matrix instead of \mathbf{M}_N . To do this we make use of an identity that may easily be derived through induction. If \mathbf{A}_N is any $N \times N$ matrix whose elements are differentiable functions of ρ , and if \mathbf{A}_N^{-1} exists, then if $\partial^s \mathbf{A}_N / \partial \rho^s \equiv \mathbf{0}_N$ (the null matrix) for s > 1,

$$\frac{\partial^k \mathbf{A}_N^{-1}}{\partial \rho^k} = (-1)^k k! \left[\mathbf{A}_N^{-1} \cdot \frac{\partial \mathbf{A}_N}{\partial \rho} \right]^k \cdot \mathbf{A}_N^{-1}.$$
(II.10)

If we identify A_N with M_N and set k = l - 2, B_l (l > 1) in Eq. (II.9) becomes

$$B_{l}(N) = \frac{(-1)^{l-1}}{N} \operatorname{Tr}[\mathbf{M}_{N}^{-1}(0) \cdot \mathbf{T}_{N}]^{l-1},$$
$$\mathbf{M}_{N}(0) = \mathbf{M}_{N}(\rho)|_{\rho=0}.$$
(II.11)

 $\mathbf{M}_{N}(0)$ is a lower triangular matrix and its inverse can be written explicitly. Using $b_{1} \equiv 1$, we have, for $\mathbf{M}_{N}(0)$,

$$\mathbf{M}_{N}(0) = \begin{cases} 1 & 0 & 0 & \cdots & 0 \\ 2b_{2} & 1 & 0 & \cdots & 0 \\ 3b_{3} & 2b_{2} & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ Nb_{N} & (N-1)b_{N-1} & (N-2)b_{N-2} & \cdots & 1 \\ \end{cases}, \quad (II.12)$$

HUBBARD

and $\mathbf{M}_{N}^{-1}(0)$ is given by [10]

Thus $\mathbf{M}_N^{-1}(0) \cdot \mathbf{T}_N$ can be written as

$$\mathbf{M}_{N}^{-1}(0) \cdot \mathbf{T}_{N} = -\frac{1}{N} \begin{cases} 0 & 1 & 0 & 0 & \cdots & 0 \\ 0 & \mu_{2} & 2 & 0 & \cdots & 0 \\ 0 & \mu_{3} & 2\mu_{2} & 3 & \cdots & 0 \\ 0 & \mu_{4} & 2\mu_{3} & 3\mu_{2} & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & & \vdots \\ 0 & \mu_{N} & 2\mu_{N-1} & 3\mu_{N-2} & \cdots & (N-1)\mu_{2} \end{cases} \right)_{N}$$
(II.14)

The substitution of Eq. (II.14) into Eq. (II.11) produces a new formula for generating the $B_i(N)$ that is well suited for computer calculations.

III. A MATRIX FORMULA FOR THE N-P-T- VIRIAL COEFFICIENTS

We begin with Eq. (II.1), collecting all factors of the volume V:

$$Q(N, V, T) = \frac{1}{A^{3N}} \sum_{\{m_i\}} V^m \prod_{l=1}^N \frac{(b_l)^{m_l}}{m_l!},$$

$$\Sigma lm_l = N,$$

$$\Sigma m_l = m.$$
(III.1)

We can write

$$Q(N, V, T) = \tilde{Q}(N, V, T) + \Delta Q(N, V, T), \qquad (\text{III.2})$$

where $\tilde{Q}(N, V, T)$ is formed from the volume independent integrals b_i and $\Delta Q(N, V, T)$ contains both the b_i and b_i' . From Eq. (II.3), we see that

$$\Delta Q(N, V, T) = 0$$
 for $L \ge L_N = aN$
or $V \ge V_N$. (III.3)

The N-P-T partition function may be written as

$$Q(N, P, T) = z \int_{0}^{\infty} dV e^{-zV} Q(N, V, T) + z \int_{0}^{V_{N}} dV e^{-zV} \Delta Q(N, V, T)$$

= $\frac{1}{A^{3N}} \Big[\frac{1}{z^{N}} \sum_{\{m_{i}\}}^{\prime} m! z^{N-m} \prod_{l=1}^{N} \frac{(b_{l})^{m_{l}}}{m_{l}!} + z \int_{0}^{V_{N}} dV e^{-zV} \sum_{\{m_{l}\}}^{\prime} V^{m} F_{n}(\{b_{l}'\}, \{b_{l}\}) \Big],$
(III.4)

the primed summations indicating that the two restrictions in Eq. (III.1) are imposed [11]. F_N is some algebraic function of the b_i and the b_i and z represents the independent variable P/k_BT . The exponential function in the last term can be expanded to give

$$\Delta Q(N, P, T) = \frac{1}{\Lambda^{3N}} \left[\frac{1}{z^N} \sum_{j=0}^{\infty} \frac{(-z)^{N+j+1}}{j!} \int_0^{V_N} dV \sum_{\{m_l\}} V^{m+j} F_N(\{b_l'\}, \{b_l\}) \right].$$
(III.5)

If we factor out the term z^{-N} from Eqs. (III.4) and (III.5) we see that the lowest power of z occurring in Eq. (III.5) is z^{N+1} while the highest power of z occurring in the first term of Eq. (III.4) is z^{N-1} since the minimum value of m is 1. It is not difficult to show that if, in the virial expansion

$$\frac{\overline{V}}{N} = -\frac{1}{N} \left(\frac{\partial \ln Q(N, P, T)}{\partial z} \right)_{N,T} = \sum_{l=1}^{\infty} C_l(N) z^{l-2}, \quad (\text{III.6})$$

we limit ourselves to the consideration of terms up to order z^{N-1} , we avoid the complication of the higher order terms due to Eq. (III.5) [12]. Thus the first term in Eq. (III.4) gives the correct virial expansion for terms up to order z^{N-1} . In the rest of this section we restrict our attention to these terms.

A new formula for Q(N, P, T) can then be written in the form [8]

$$Q(N, P, T) = \frac{1}{A^{3N}z^{N}} \det \mathbf{P}_{N}$$

$$\mathbf{P}_{N} = \begin{cases} b_{1} & -z & 0 & 0 & \cdots & 0 \\ b_{2} & b_{1} & -z & 0 & \cdots & 0 \\ b_{3} & b_{2} & b_{1} & -z & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ b_{N} & b_{N-1} & b_{N-2} & b_{N-3} & \cdots & b_{1} \end{cases}_{N}$$
(III.7)

HUBBARD

Following the procedure in Section II, the equation of state may be written as

$$\frac{\overline{V}}{N} = \frac{1}{z} - \frac{1}{N} \left(\frac{\partial \ln \Gamma_N}{\partial z} \right)_{N,T} = \frac{1}{z} - \frac{1}{N} \operatorname{Tr} \left[\mathbf{P}_N^{-1} \cdot \left(\frac{\partial \mathbf{P}_N}{\partial z} \right)_{N,T} \right]$$
$$\Gamma_N = \det \mathbf{P}_N, \qquad (III.8)$$

where

$$\left(\frac{\partial \mathbf{P}_{N}}{\partial z}\right)_{N,T} = \mathbf{W}_{N} = - \begin{cases} 0 & 1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & 0 \\ \end{pmatrix}_{N}$$
(III.9)

The virial expansion becomes

$$\frac{\overline{V}}{N} = \sum_{l=1}^{N+1} C_l(N) z^{l-2} = \frac{1}{z} + \sum_{l=2}^{N+1} \frac{(-1)}{N(l-2)!} \frac{\partial^{l-2}}{\partial z^{l-2}} (\operatorname{Tr} \mathbf{P}_N^{-1} \cdot \mathbf{W}_N) \Big|_{z=0} z^{l-2}$$
$$= \frac{1}{z} + \sum_{l=2}^{N+1} \frac{(-1)}{N(l-2)!} \operatorname{Tr} \left[\left(\frac{\partial^{l-2} \mathbf{P}_N^{-1}}{\partial z^{l-2}} \right)_{z=0} \cdot \mathbf{W}_N \right] z^{l-2}.$$
(III.10)

We use Eq. (II.10) to simplify Eq. (III.10) so that C_l (l > 1) in Eq. (III.10) becomes

$$C_{l}(N) = \frac{(-1)^{l-1}}{N} \operatorname{Tr}[\mathbf{P}_{N}^{-1}(0) \cdot \mathbf{W}_{N}]^{l-1},$$
$$\mathbf{P}_{N}(0) = \mathbf{P}_{N}(z) |_{z=0}, \qquad (\text{III.11})$$

which closely resembles Eq. (II.11). Again taking $b_1 \equiv 1$, we have for $\mathbf{P}_N(0)$

$$\mathbf{P}_{N}(0) = \begin{cases} 1 & 0 & 0 & \cdots & 0 \\ b_{2} & 1 & 0 & \cdots & 0 \\ b_{3} & b_{2} & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & & \vdots \\ b_{N} & b_{N-1} & b_{N-2} & \cdots & 1 \\ \end{pmatrix}_{N}$$
(III.12)

and $\mathbf{P}_N^{-1}(0)$ is given by

$$\mathbf{P}_{N}^{-1}(0) = \begin{cases} 1 & 0 & 0 & \cdots & 0 \\ t_{2} & 1 & 0 & \cdots & 0 \\ t_{3} & t_{2} & 1 & \cdots & 0 \\ t_{4} & t_{3} & t_{2} & \cdots & 0 \\ \vdots & \vdots & \vdots & & \vdots \\ t_{N} & t_{N-1} & t_{N-2} & \cdots & 1 \\ \end{cases}_{N}^{*}$$

$$t_{j} = (-1)^{j-1} \begin{vmatrix} b_{2} & 1 & 0 & \cdots & 0 \\ b_{3} & b_{2} & 1 & \cdots & 0 \\ b_{4} & b_{3} & b_{2} & \cdots & 0 \\ \vdots & \vdots & \vdots & & \vdots \\ b_{j} & b_{j-1} & b_{j-2} & \cdots & b_{2} \end{vmatrix}_{j-1}^{*}.$$
(III.13)

Thus $\mathbf{P}_N^{-1}(0) \cdot \mathbf{W}_N$ can be written as

$$\mathbf{P}_{N}^{-1}(0) \cdot \mathbf{W}_{N} = - \begin{pmatrix} 0 & 1 & 0 & 0 & \cdots & 0 \\ 0 & t_{2} & 1 & 0 & \cdots & 0 \\ 0 & t_{3} & t_{2} & 1 & \cdots & 0 \\ 0 & t_{4} & t_{3} & t_{2} & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & t_{N} & t_{N-1} & t_{N-2} & \cdots & t_{2} \end{pmatrix}_{N}$$
(III.14)

The substitution of Eq. (III.14) into Eq. (III.11) gives us a matrix algorithm for generating the $C_l(N)$. This is also a new result.

Since most of the numerical results on virial coefficients are presented in terms of the irreducible cluster integrals β_k (for an infinite system), we express b_j in terms of the β_k [6]:

$$b_{j} = \frac{1}{j^{2}} \sum_{\{n_{k}\}}^{j} \prod_{k=1}^{j-1} \frac{(j\beta_{k})^{n_{k}}}{n_{k}!},$$
$$\sum_{k=1}^{j-1} kn_{k} = j - 1, \qquad (\text{III.15})$$

or in determinental form [8]:

$$b_{j} = \frac{1}{j^{2}(j-1)!} \begin{vmatrix} j\beta_{1} & -1 & 0 & \cdots & 0\\ 2jb_{2} & j\beta_{1} & -2 & \cdots & 0\\ 3j\beta_{3} & 2j\beta_{2} & j\beta_{1} & \cdots & 0\\ 4j\beta_{4} & 3j\beta_{3} & 2j\beta_{2} & \cdots & 0\\ \vdots & \vdots & \vdots & \vdots\\ (j-1)j\beta_{j-1} & (j-2)j\beta_{j-2} & (j-3)j\beta_{j-3} & \cdots & j\beta_{1} \end{vmatrix}_{j-1} .$$
(III.16)

The β_k are defined by [6]

$$\beta_k = \frac{1}{k! V} \int \cdots_{\nu} \int S_{1,2,\cdots,k+1} \, d\mathbf{r}_1 \cdots d\mathbf{r}_{k+1} \,, \qquad (\text{III.17})$$

where $S_{1,2,\ldots,k+1}$ is defined as the sum over all products of Mayer *f*-functions such that for a particular product the *f*-bonds between the labeled points form a labeled graph on k + 1 points distinct from any other labeled graph on k + 1 points and which has at least two independent paths along *f*-bonds which do not cross at any point for each pair of labeled points in the labeled graph. We define the *f*-function by

$$f_{ij} = \exp(-\varphi_{ij}/k_B T) - 1, \qquad \text{(III.18)}$$

where φ_{ij} is a pair potential.

The density-virial coefficients for an infinite system, $B_l(\infty)$ (see Eq. (II.9)), are related to the β_k by

$$B_{l}(\infty) = -\frac{l-1}{l}\beta_{l-1}$$
. (III.19)

IV. Algebraic Expressions for the Virial Coefficients $B_l(N)$ and $C_l(N)$

We now recall Wood's result for $B_l(N)$, $1 \le l \le 5$, described by Eq. (II.9) and Eq. (II.11) in terms of the $B_l(\infty)$ (or simply B_l) [1]:

$$\begin{split} B_1(N) &= 1, \\ B_2(N) &= B_2 - B_2 N^{-1}, \\ B_3(N) &= B_3 + (2B_2{}^2 - 3B_3) N^{-1} + (-2B_2{}^2 + 2B_3) N^{-2}, \\ B_4(N) &= B_4 + (-4B_2{}^3 + 9B_2B_3 - 6B_4) N^{-1} + (16B_2{}^3 - 27B_2B_3 + 11B_4) N^{-2} \\ &+ (-12B_2{}^3 + 18B_2B_3 - 6B_4) N^{-3}, \\ B_5(N) &= B_5 + (-24B_2{}^2B_3 + 9B_3{}^2 + 16B_2B_4 - 10B_5 + 8B_2{}^4) N^{-1} \\ &+ (192B_2{}^2B_3 - 51B_3{}^2 - 96B_2B_4 + 35B_5 - 80B_2{}^4) N^{-2} \\ &+ (-408B_2{}^2B_3 + 90B_3{}^2 + 176B_2B_4 - 50B_5 + 192B_2{}^4) N^{-3} \\ &+ (240B_2{}^2B_3 - 48B_3{}^2 - 96B_2B_4 + 24B_5 - 120B_2{}^4) N^{-4}. \end{split}$$

The $C_l(N)$ (see Eqs. (III.10) and (III.11)) for $1 \le l \le 7$, expressed in terms of the $C_l(\infty)$ (or simply C_l) are given by

$$C_{1}(N) = 1,$$

$$C_{2}(N) = C_{2} - C_{2}N^{-1},$$

$$C_{3}(N) = C_{3} + (C_{2}^{2} - 2C_{3})N^{-1},$$

$$C_{4}(N) = C_{4} + (-C_{2}^{3} + 3C_{2}C_{3} - 3C_{4})N^{-1},$$

$$C_{5}(N) = C_{4} + (C_{2}^{4} + 4C_{3}C_{4} - 4C_{3}C_{2}^{2} + 2C_{3}^{2} - 4C_{5})N^{-1},$$

$$C_{6}(N) = C_{6} + (-C_{2}^{5} + 5C_{3}C_{2}^{3} - 5C_{3}^{2}C_{2} - 5C_{4}C_{2}^{2} + 5C_{3}C_{4} + 5C_{2}C_{5} - 5C_{6})N^{-1},$$

$$C_{7}(N) = C_{7} + (C_{2}^{6} - 2C_{3}^{3} + 9C_{2}^{2}C_{3}^{2} - 6C_{2}^{4}C_{3} + 6C_{2}^{3}C_{4} - 12C_{2}C_{3}C_{4} + 3C_{4}^{2} - 6C_{5}C_{2}^{2} + 6C_{2}C_{6} + 6C_{3}C_{5} - 6C_{7})N^{-1}.$$
(IV.2)

The $C_l(\infty)$ may be expressed in terms of the more familiar $B_l(\infty)$, the relationship being [13]

$$\begin{split} C_2 &= B_2 \,, \\ C_3 &= B_3 - B_2^2 , \\ C_4 &= B_4 - 3B_2B_3 + 2B_2^3 , \\ C_5 &= B_5 - 4B_2B_4 + 10B_2^2B_3 - 2B_3^2 - 5B_2^4 , \\ C_6 &= B_6 - 5B_2B_5 - 5B_3B_4 + 15B_2B_3^2 + 15B_2^2B_4 - 35B_2^3B_3 + 14B_2^5 , \\ C_7 &= B_7 - 6B_2B_6 - 6B_3B_5 - 3B_4^2 + 7B_3^2 + 42B_2B_3B_4 + 21B_2^2B_5 - 84B_2^2B_3^2 \\ &\quad - 56B_2^3B_4 + 126B_2^4B_3 - 42B_2^6 . \end{split}$$
 (IV.3)

For hard spheres of diameter σ ,

$$B_{2} = \frac{2\pi}{3} \sigma^{3},$$

$$B_{2}/B_{2} = 1,$$

$$B_{3}/B_{2}^{2} = 0.62500,$$

$$B_{4}/B_{2}^{3} = 0.28695,$$

$$B_{5}/B_{2}^{4} = 0.1103 \pm .0003,$$

$$B_{6}/B_{2}^{5} = 0.0386 \pm .0004,$$

$$B_{7}/B_{2}^{6} = 0.0138 \pm .0004 \quad [14],$$

(IV.4)

so that

$$\begin{split} &C_2(N)/B_2 = 1 - N^{-1}, \\ &C_3(N)/B_2{}^2 = -0.3750 + 1.7500 \ N^{-1}, \\ &C_4(N)/B_2{}^3 = 0.41195 - 3.3609 \ N^{-1}, \\ &C_5(N)/B_2{}^4 = (-.56875 \pm .0003) + (6.7041 \pm .0012) \ N^{-1}, \\ &C_6(N)/B_2{}^5 = (0.8790 \pm .0019) + (-13.6490 \pm .0110) \ N^{-1}, \\ &C_7(N)/B_2{}^6 = (-1.4524 \pm .0102) + (28.1363 \pm .0751) \ N^{-1}, \end{split}$$

V. THE PADÉ APPROXIMATION TO THE *N-P-T* EQUATION OF STATE FOR HARD SPHERES

Equation (III.10) may be written in the form

$$\frac{P\overline{V}}{Nk_{B}T} = 1 + z'[C_{2}/B_{2} + (C_{3}/B_{2}^{2})(z')^{2} + \cdots] + \frac{z'}{N}[C_{2}^{(N)}/B_{2} + (C_{3}^{(N)}/B_{2}^{2})(z')^{2} + \cdots], \qquad (V.1)$$

where $z' = B_2 z$, the C_l are the *N-P-T* virial coefficients for the infinite system and $C_l^{(N)}$ is the coefficient of N^{-1} in $C_l(N)$ ($C_l(N) = C_l + C_l^{(N)} N^{-1}$).

We form the Padé approximation to Eq. (V.1) by introducing

$$\frac{P\overline{V}}{Nk_{B}T} = 1 + z'P^{(\infty)}(n,m) + \frac{z'}{N}P^{(N)}(n,m), \qquad (V.2)$$

where the P(n, m) are defined by [15]

$$P(n,m) = \frac{\sum_{i=1}^{n} \alpha_i(z')^i}{1 + \sum_{i=1}^{m} \gamma_i(z')^i}.$$
 (V.3)

The α 's and γ 's are constants determined by the substitution of Eq. (V.3) into Eq. (V.1). For hard spheres, the $C_l(N)$ for $2 \leq l \leq 7$ are given by Eq. (IV.5) so for this system the α 's and γ 's are uniquely determined for $n + m \leq 7$.

Since we are dealing with a hard core system, it is convenient to introduce the close packed volume V_0 into Eqs. (V.2) and (V.3), where

$$V_0 = N\sigma^3/\sqrt{2} \tag{V.4}$$

for hard spheres of diameter σ . The variable z' may then be expressed as

$$z' = \frac{2\sqrt{2}\pi}{3}\varphi,$$

$$\varphi = PV_0/Nk_BT.$$
 (V.5)

If we express Eq. (V.2) in terms of φ and define the dependent variable

$$\tau = \overline{V}/V_0, \qquad (V.6)$$

Eq. (V.2) becomes

$$\tau \varphi = \varphi \tau^{(\infty)}(n,m) + \frac{\varphi}{N} \tau^{(N)}(n,m), \qquad (V.7)$$

where

$$\tau^{(\infty)}(n,m) = \varphi^{-1} + \frac{2\sqrt{2} \pi}{3} P^{(\infty)}(n,m),$$

$$\tau^{(N)}(n,m) = \frac{2\sqrt{2} \pi}{3} P^{(N)}(n,m) \quad [16]. \tag{V.8}$$

TABLE I

The Padé Approximants $\tau^{(\infty)}(n, m)$ and $\tau^{(N)}(n, m)$ as a function of $\varphi = PV_0/Nk_BT$ for hard spheres in an *N*-*P*-*T* ensemble^a

φ	$\tau^{(\infty)}(4, 3)$	$\tau^{(\infty)}(3, 4)$	$\tau^{(\infty)}(3,3)$	$\tau^{(N)}(4, 3)$	$\tau^{(N)}(3,4)$	$\tau^{(N)}(3, 3)$
.50	4.25	4.25	4.27	894	898	904
.75	3.43	3.44	3.47	669	679	692
1.00	2.99	2.99	3.05	529	549	567
1.25	2.68	2.70	2.79	429	461	485
1.50	2.45	2.48	2.61	352	398	426
2.00	2.12	2.19	2.37	235	313	349
3.00	1.67	1.82	2.13	070	220	266

^a V_0 is the close packed volume, P is the pressure, N the number of spheres, k_B Boltzmann's constant and T is the absolute temperature.

Table I gives the $\tau^{(\infty)}$ and $\tau^{(N)}$ as a function of φ for various *n* and *m*. We restrict our attention to the cases $n = m \pm 1$ and n = m, since these produce the most consistent results. The stability of the Padé approximation is remarkable considering the fact that the C_l and $C_l^{(N)}$ in Eq. (IV.5) alternate in sign and increase in absolute value as *l* increases. The largest deviation from the arithmetic mean of $\tau^{(\infty)}$ at $\varphi = 2$ is 6.3% of the mean.

HUBBARD

A comparison between Table I and the molecular dynamics studies of Alder and Wainwright [2] can be made in the region where N is so large that finite N effects can be neglected and $\tau^{(\infty)}(4, 3)$, $\tau^{(\infty)}(3, 4)$ and $\tau^{(\infty)}(3, 3)$ can be taken as constant for a given φ . For $\varphi = 1.00$, Table I gives $P\overline{V}/Nk_BT \approx 3.01$ while Alder and Wainwright give $PV/Nk_BT \approx 3.05$.

For larger values of φ ($\varphi > 2$) agreement with the molecular dynamics results seems to be rather poor when compared with the agreement Ree and Hoover oqtained with a Padé treatment of the 6 and 7 term virial series in an *N*-*V*-*T* formalism [14]. However, the main test of the usefulness of the *N*-*P*-*T* formalism will be the comparison of Eqs. (V.7) and (V.8) with the results of computer experiments performed directly in the *N*-*P*-*T* ensemble.

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- 16. If we had defined Q(N, P, Y) as $\int_0^\infty e^{-sV} \tilde{Q}(N, V, T) dV$ instead of as the first term in Eq. (III. 4), $C_1(N)$ would be $1 + N^{-1}$ instead of 1. $\tau^{(\infty)}$ would not change but $\tau^{(N)}$ would be $\varphi^{-1} + (2\sqrt{2}\pi)/3 P^{(N)}$ instead of $(2\sqrt{2}\pi)/3 P^{(N)}$.